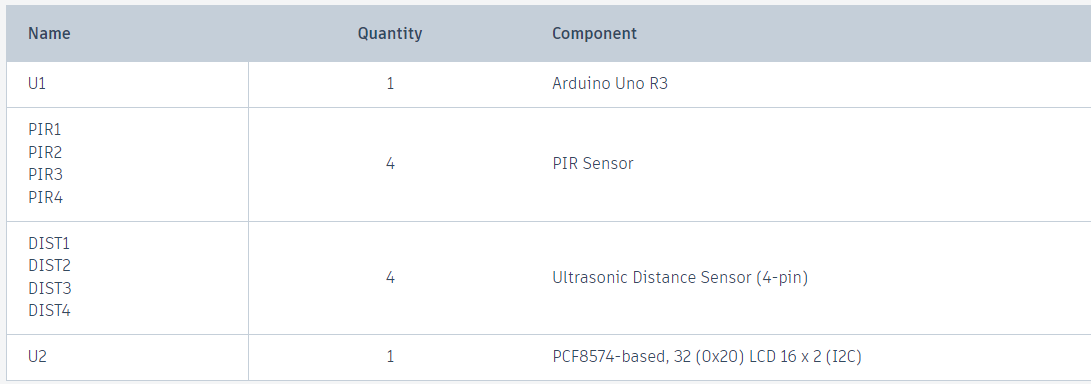
# Radar System

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*EC23B1075*

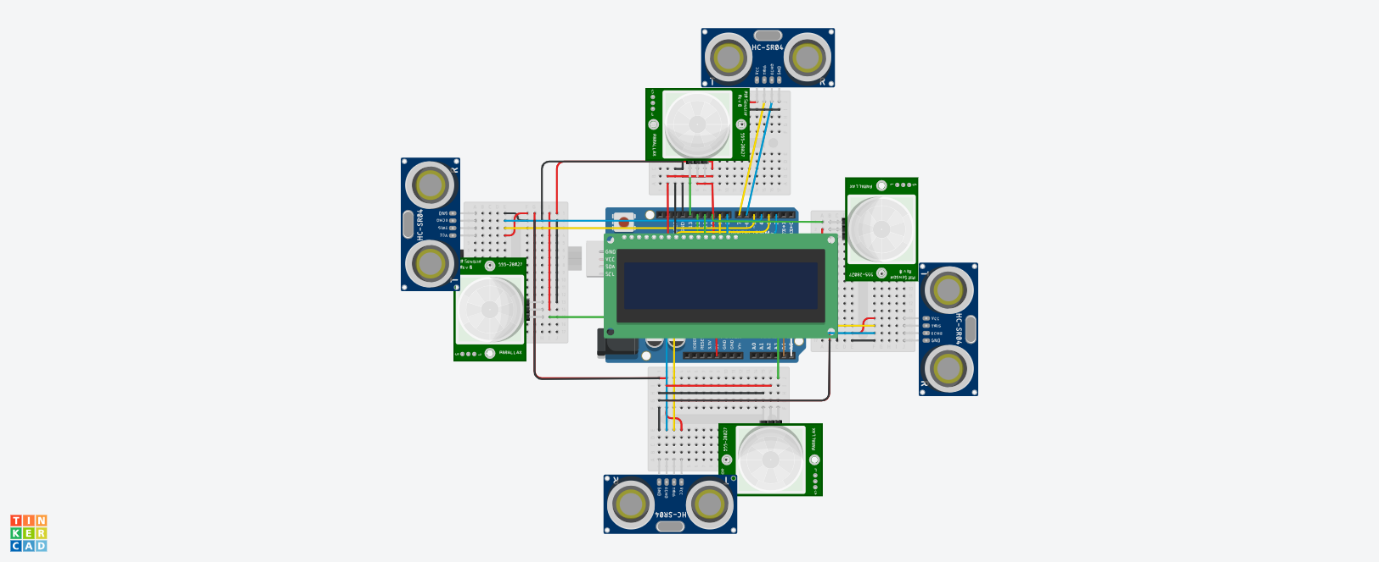
**Components used:**

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**Working:**

In this project the PIR sensors detect the presence of a moving object in a particular direction. The ultrasonic sensor in that direction is then turned On and the distance of moving object is calculated.

**Picture**

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**TinkerCad Link:** https://www.tinkercad.com/things/fgXqWFdkTPV-radar-system-?sharecode=s0aeWrS9bWD5pu4LzllHvVWJfpHOz4p7gUeNRJP1QfI